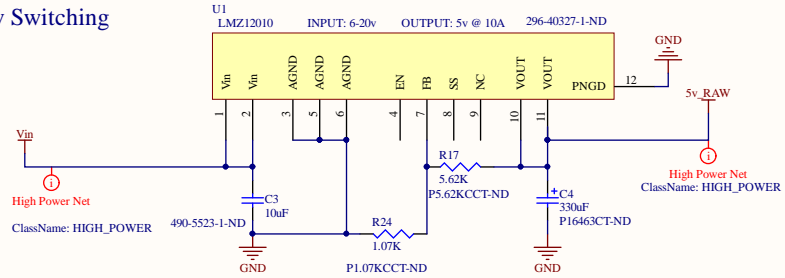
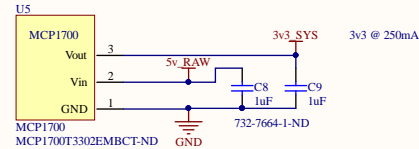


### SYS 5v Switching

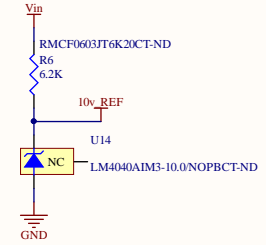


### 3v3 Linear



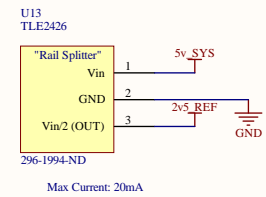
### Precision Voltage References

#### 10v Reference

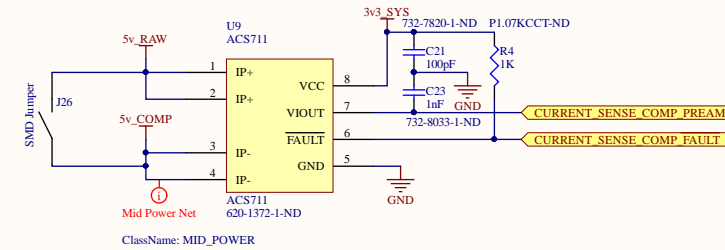
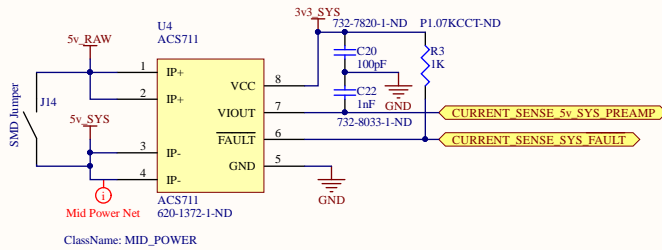
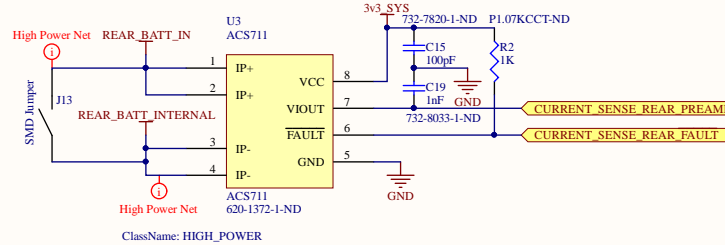
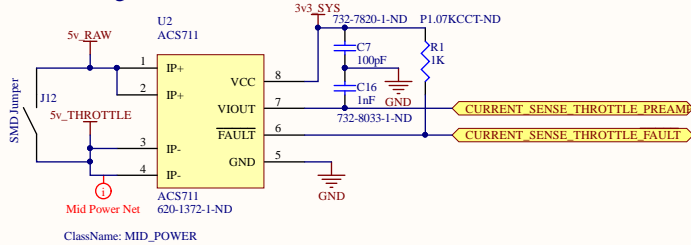


Note: Assumed calculated current of 2mA minimum required current is 100uA

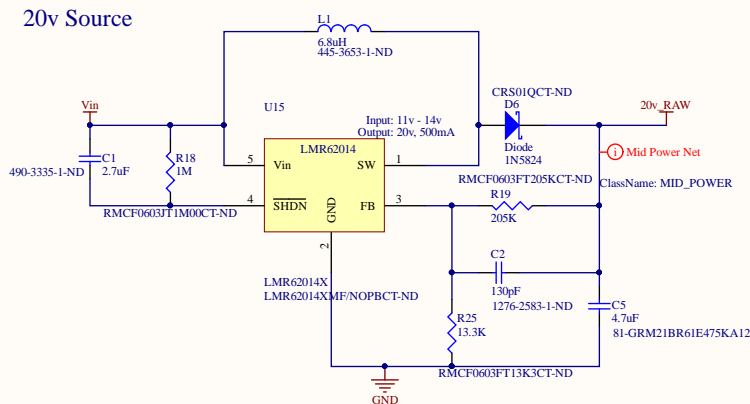
#### 2v5v Reference



### Current Sensing



### 20v Source



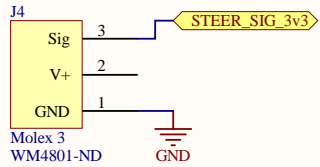
### GND Power Classification



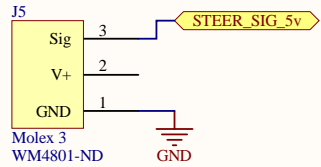
Note: Even though GND is classified as "MID\_POWER" parts of it must be manually routed as "HIGH\_POWER" and the GND plane takes care of the rest.

Title PowerManagement.SchDoc			Ocean Mixing Group Oregon State University Corvallis, OR		
Size: A4	Number: 1	Engineer: Nick McComb			
Date: 3/1/2016	Time: 12:41:07 PM	Sheet 1 of 7			
File: C:\Users\npic_000\Google Drive\PCB Designs\ROSSPowerDistribution\PowerManagement.SchDoc					

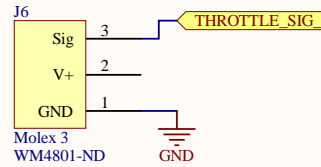
### Steering Input



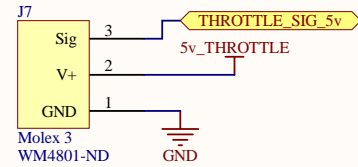
### Steering Output



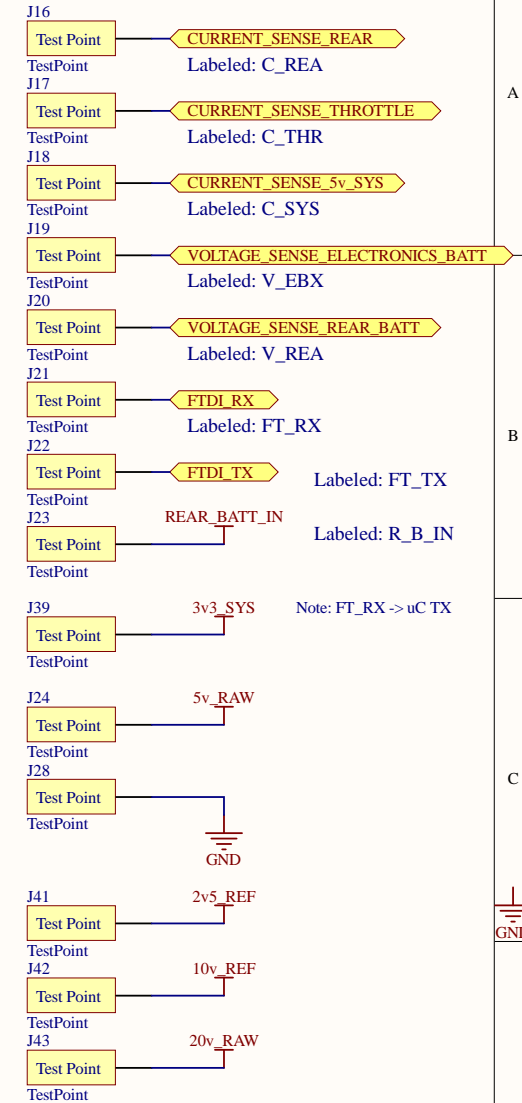
### Throttle Input



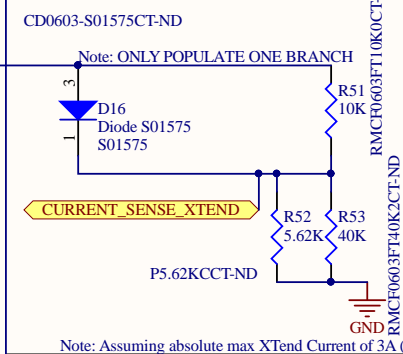
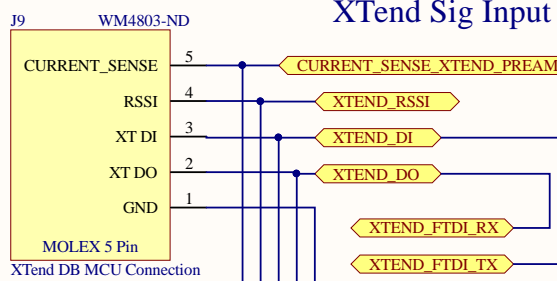
### Throttle Output



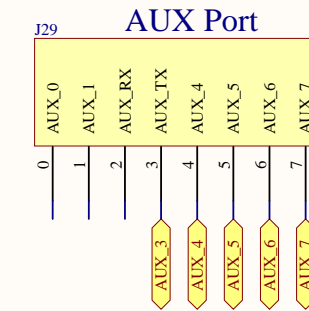
### Test Points



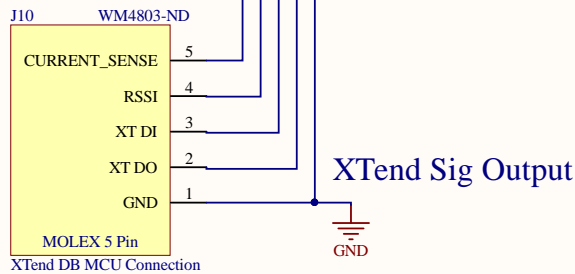
### XTend Sig Input



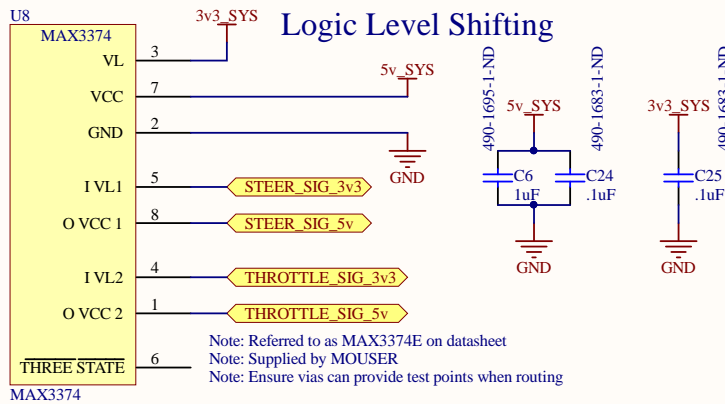
### Aux Port



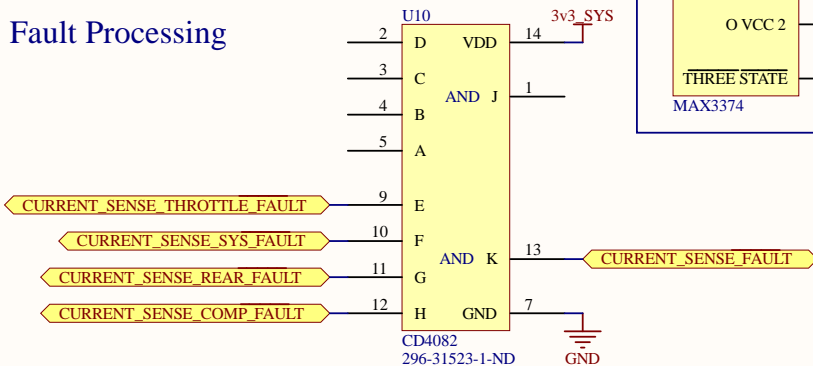
### XTend Sig Output

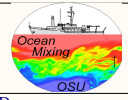


### Logic Level Shifting

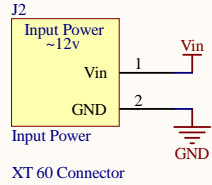


### Fault Processing

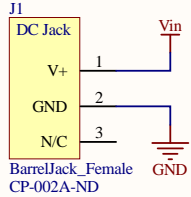


Title		SignalProcessing_SchDoc		
Size:	A4	Number:	3	
Date:	3/1/2016	Engineer:	Nick McComb	
File:	C:\Users\nrpc\000\Google Drive\PCB Designs\ROSSPowerDistribution\SignalProcessing_SchDoc			
Time:		12:41:07 PM Sheet 3 of 7		Ocean Mixing Group Oregon State University Corvallis, OR

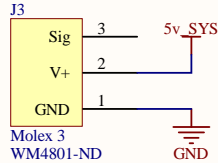
### Power Input



### XTend Power Output

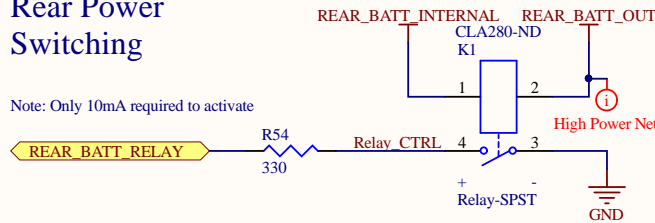


### R/C Receiver

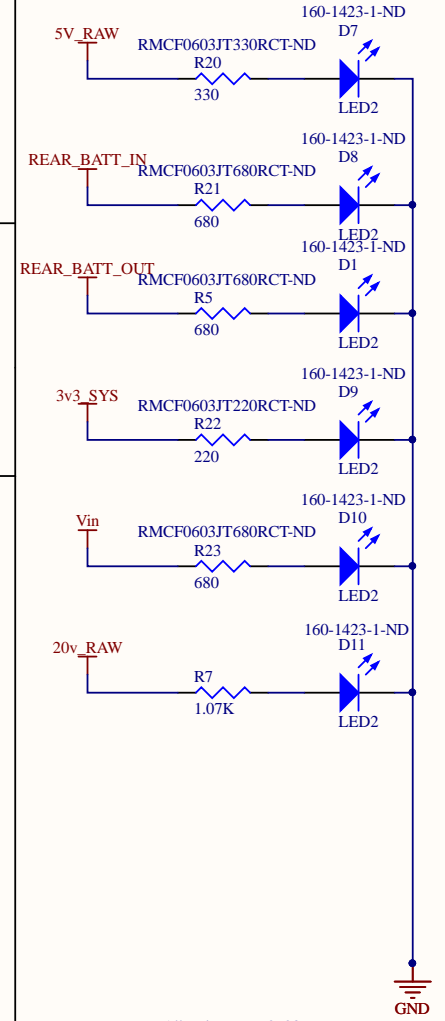


### Rear Power Switching

Note: Only 10mA required to activate

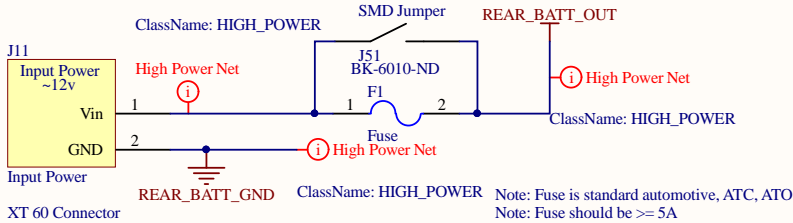
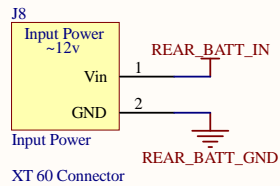


### Power Status LEDs

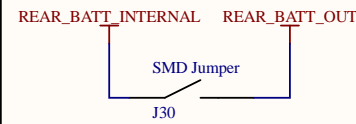


Note: All resistors are 0603

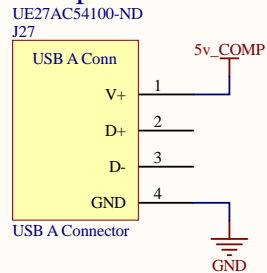
### Rear Power I/O



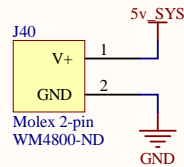
### Rear Manual Bypass



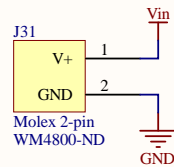
### Computer Power Connection



### Arduino UNO Power

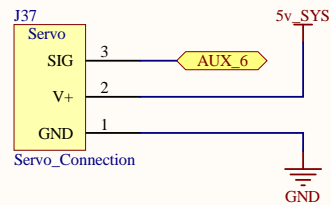
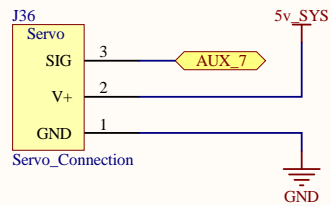


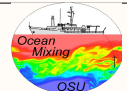
### Iridium Beacon Power



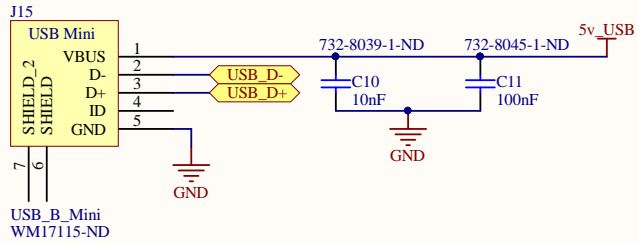
Note: Place close to input voltage

### AUX Power Access Points

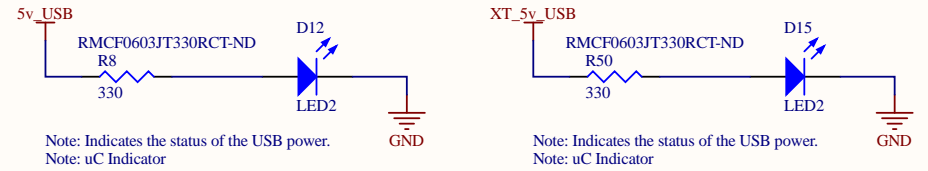


Title PowerDistribution.SchDoc			 Ocean Mixing Group Oregon State University Corvallis, OR
Size: A4	Number: 3	Engineer: Nick McComb	
Date: 3/1/2016	Time: 12:41:08 PM Sheet 3 of 7		
File: C:\Users\nrpc.000\Google Drive\PCB Designs\ROSSPowerDistribution\PowerDistribution.SchDoc			

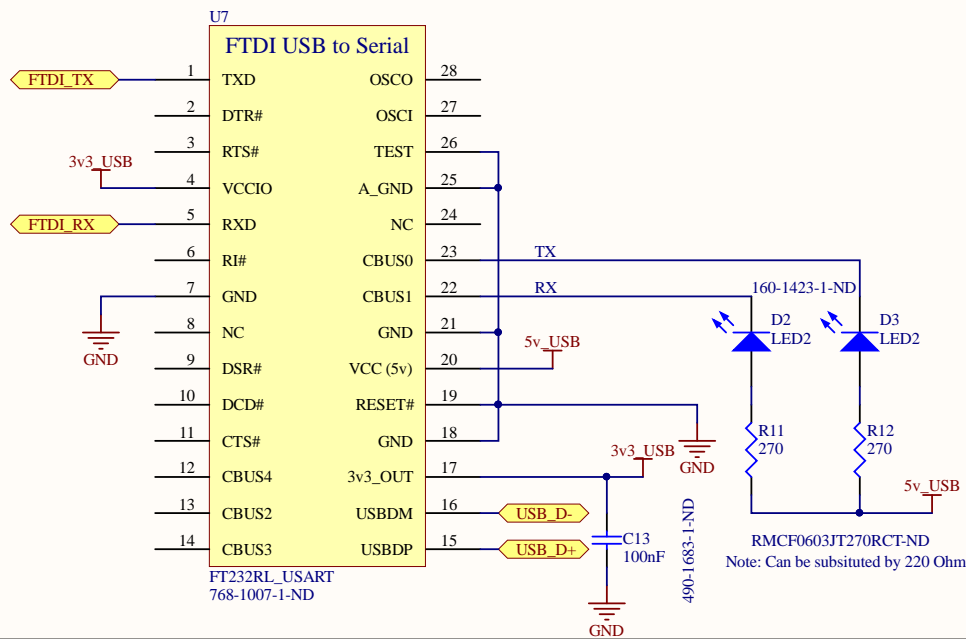
### Microcontroller USB Connection



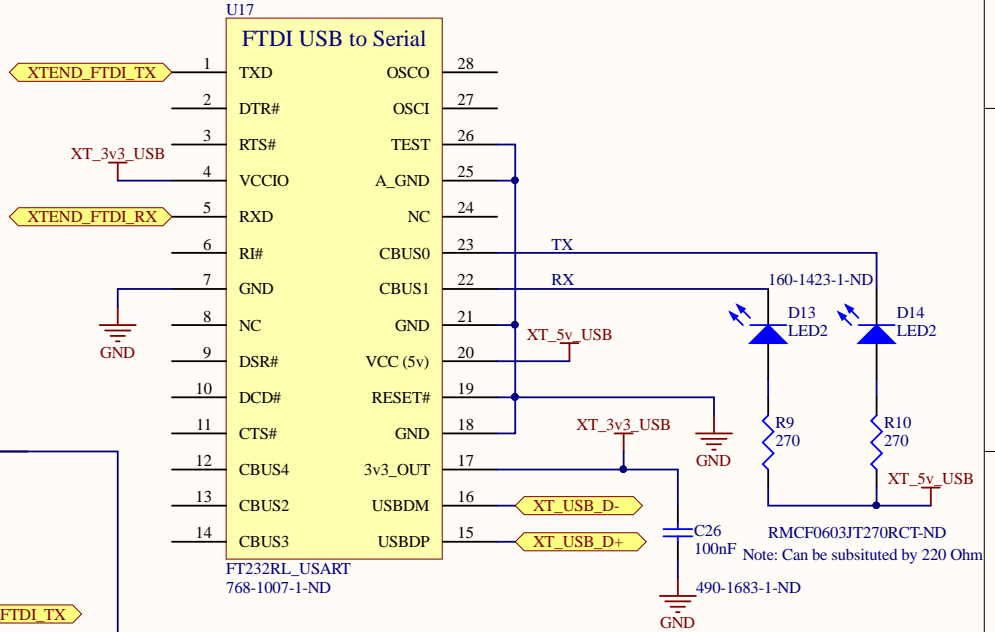
### FTDI Status Indicators



### Onboard Microcontroller FTDI

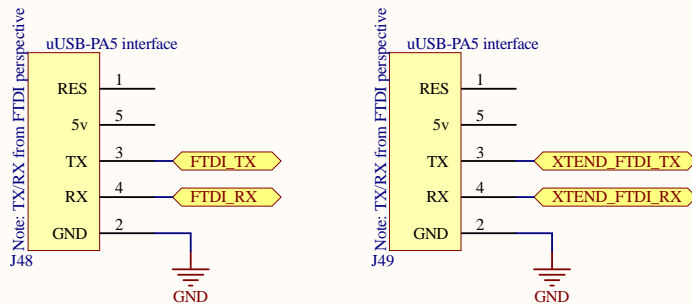


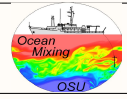
### XTend FTDI

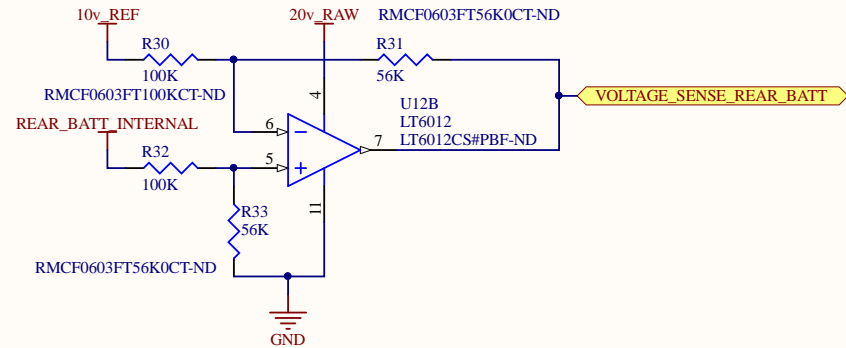
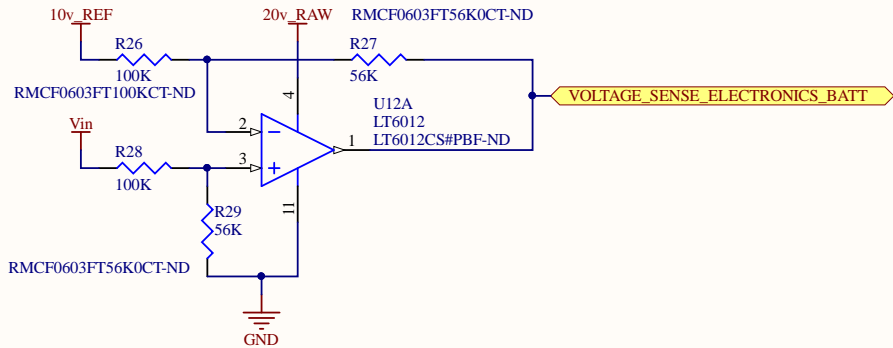


### USB To Serial IC (FTDI)

Note: Backup, do not populate unless onboard FTDI chips do not work

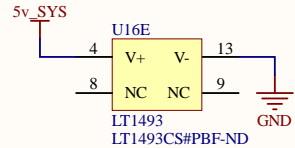
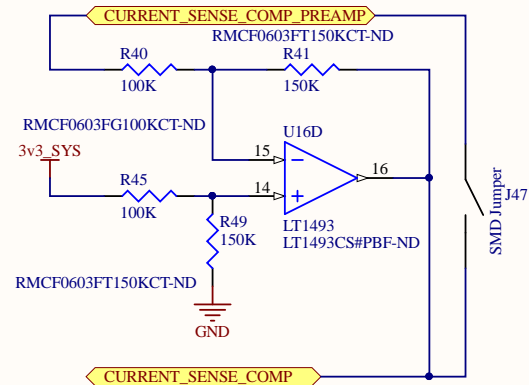
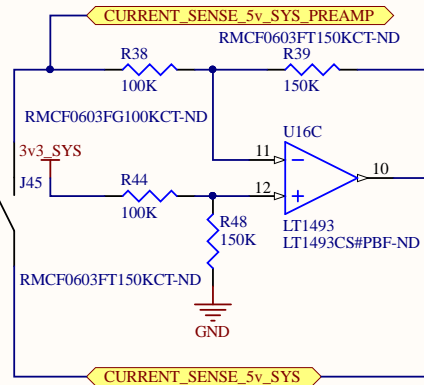
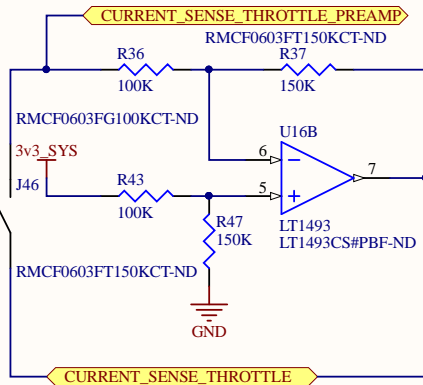
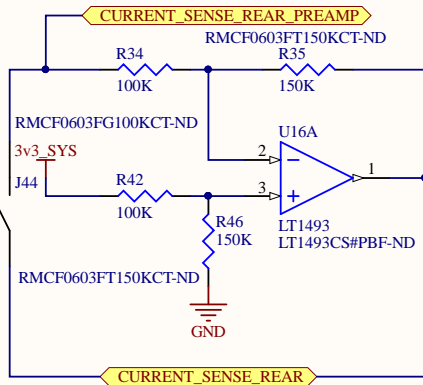
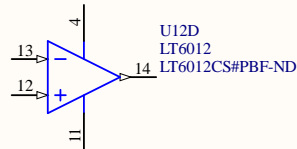
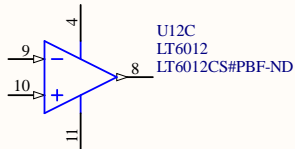


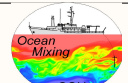
Title FTDI.SchDoc			 Ocean Mixing Group Oregon State University Corvallis, OR
Size: A4	Number: 4	Engineer: Nick McComb	
Date: 3/1/2016	Time: 12:41:08 PM Sheet 4 of 7		
File: C:\Users\npic.000\Google Drive\PCB Designs\ROSSPowerDistribution\FTDI.SchDoc			



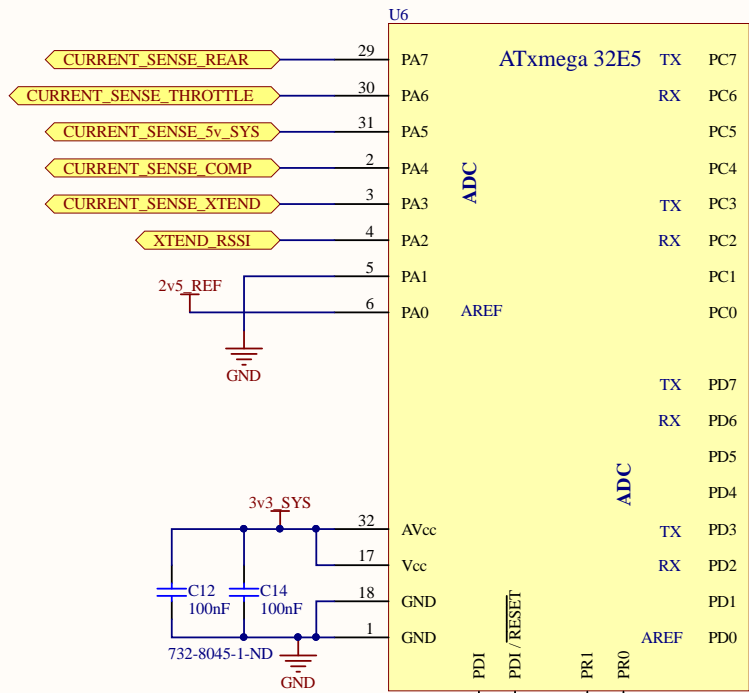
Note: VOLTAGE\_SENSE\_ELECTRONICS\_BATT can be calculated as the following:  $VEBAT = (Vin - 10.0v) * .825$

Note: VOLTAGE\_SENSE\_ELECTRONICS\_BATT can be calculated as the following:  $VEBAT = (Vin - 10.0v) * .825$

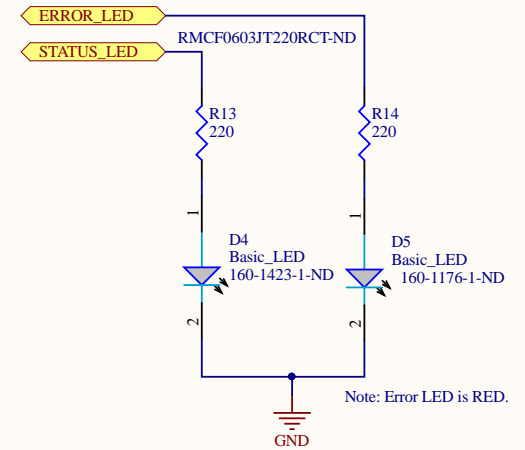


Title SignalProcessing_Amplifiers.SchDoc			Ocean Mixing Group Oregon State University Corvallis, OR	
Size: A4	Number: 5	Engineer: Nick McComb		
Date: 3/1/2016	Time: 12:41:08 PM Sheet 5 of 7			
File: C:\Users\nrpc_000\Google Drive\PCB Designs\ROSSPowerDistribution\SignalProcessing_Amplifiers.SchDoc				

# MCU



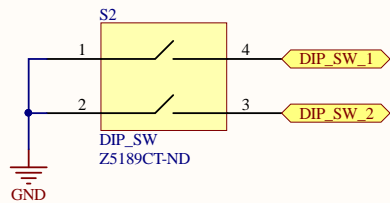
# MCU LEDs



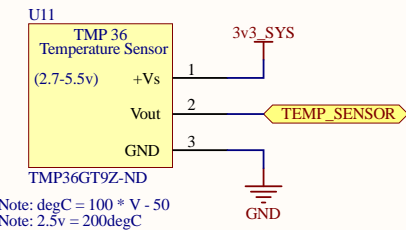
# XMega ADC Application Notes

Note: One of the first 7 channels needs to be GND, for our reference  
 Note: AREFA and AREFD are pin 0  
 Note: They need to be fed 3.3-6 volts

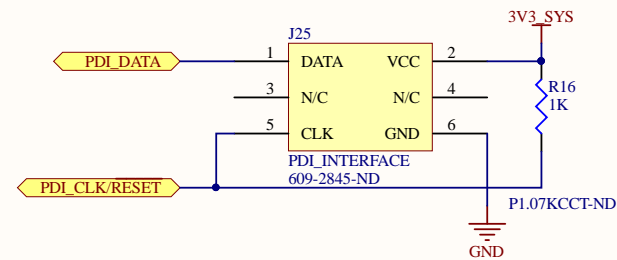
# Settings Switch



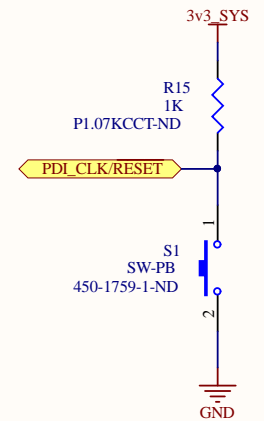
# Temperature Sensor



# MCU PDI



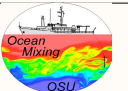
# MCU Reset

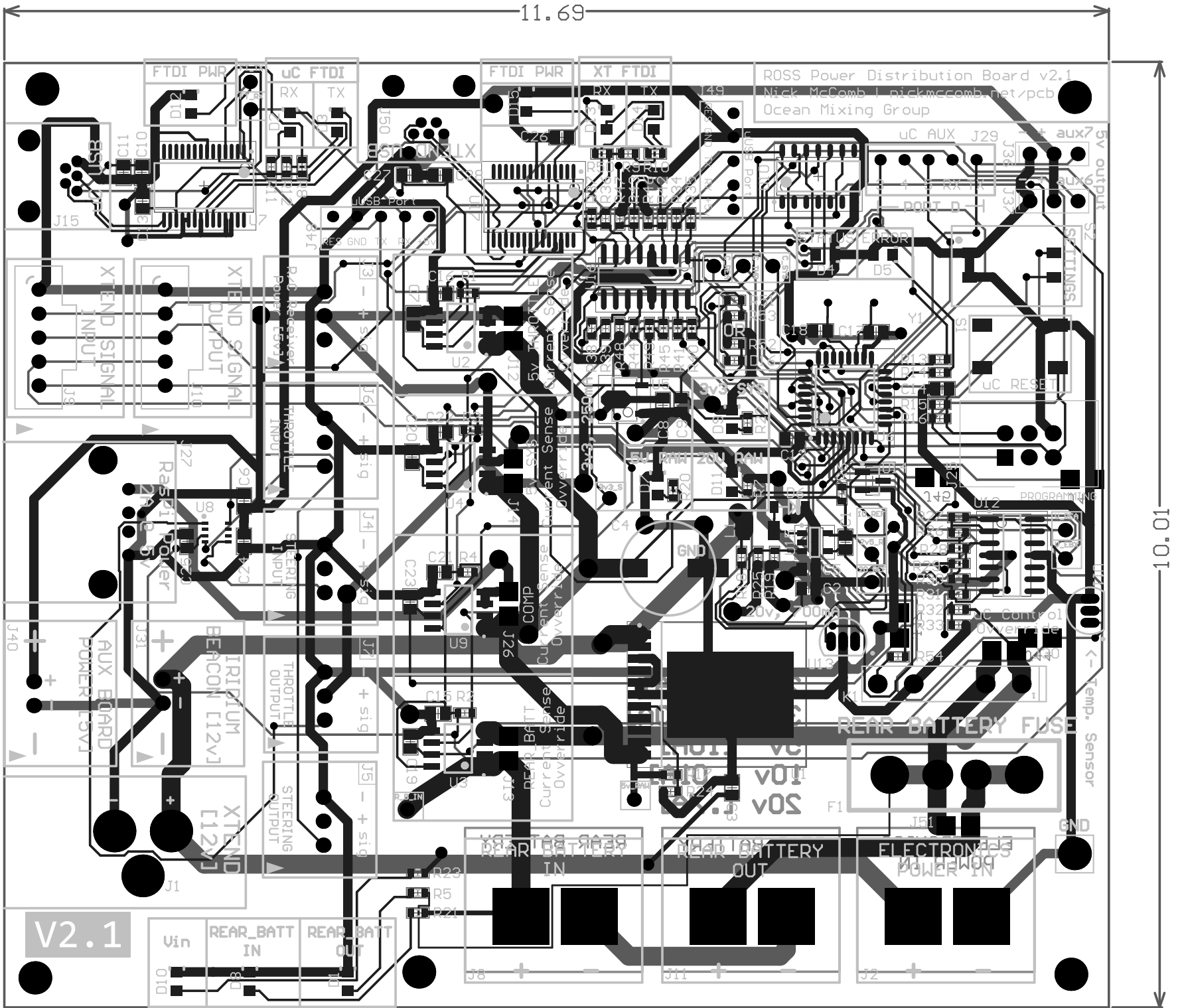


Title Microcontroller.SchDoc			Ocean Mixing Group Oregon State University Corvallis, OR	
Size: A4	Number: 6	Engineer: Nick McComb		
Date: 3/1/2016	Time: 12:41:08 PM Sheet 6 of 7			
File: C:\Users\nrpc_000\Google Drive\PCB Designs\ROSSPowerDistribution\Microcontroller.SchDoc				

# Mounting Hardware

- J32  
Mounting Hole  
MountingHoles
- J33  
Mounting Hole  
MountingHoles
- J38  
Mounting Hole  
MountingHoles
- J34  
Mounting Hole  
MountingHoles
- J35  
Mounting Hole  
MountingHoles

Title Hardware.SchDoc			<i>Ocean Mixing Group Oregon State University Corvallis, OR</i>	
Size: A4	Number: 7	Engineer: Nick McComb		
Date: 3/1/2016	Time: 12:41:08 PM Sheet 7 of 7			
File: C:\Users\nrpc.000\Google Drive\PCB Designs\ROSSPowerDistribution\Hardware.SchDoc				



11.69

10.01

V2.1

ROSS Power Distribution Board v2.1  
Nick McComb | nick@nccomb.net/pcb  
Ocean Mixing Group

ViN REAR\_BATT IN REAR\_BATT OUT

ELECTRONIC POWER IN

REAR BATTERY OUT

REAR BATTERY IN

REAR BATTERY FUSE

Temp. Sensor

PROGRAMMING

uC RESET

uC AUX

5V output

aux7

aux6

aux5

aux4

aux3

aux2

aux1

aux0

aux-1

aux-2

aux-3

aux-4

aux-5

aux-6

aux-7

aux-8

aux-9

aux-10

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